Software Verification

Matthew Parkinson Lent 2010 (16 Lectures)

Part III: Concurrency

I recommend you read Peter O'Hearn's paper on concurrent separation logic:

2

Resources, Concurrency and Local Reasoning http://www.eecs.qmul.ac.uk/~ohearn/papers/concurrency.pdf

O'Hearn has some tutorial slides that accompany the paper http://www.eecs.qmul.ac.uk/~ohearn/papers/etapstalk.pdf

Francesco Zappa-Nardelli has some very nice slides on concurrency verification:

http://moscova.inria.fr/~zappa/teaching/mpri/2009/

Many of the slides in this section of the notes have been adapted from this course.

Overview

Part 3: Concurrency Concurrency Examples Disjoint Concurrency Concurrent Separation Logic Owicki/Gries method Rely-guarantee Current/Future research

Examples of concurrency

4

Concurrency

Concurrent:

"Running together in space, as parallel lines; going on side by side, as proceedings; occurring together, as events or circumstances; existing or arising together; conjoint"

- Oxford English Dictionary

Motivation

• Concurrency is hard:

"If you can get away with it, avoid using threads. Threads can be difficult to use, and they make programs harder to debug." Java Sun Tutorial "Threads and Swing"

• Multi-core means concurrency everywhere!

Testing is hard

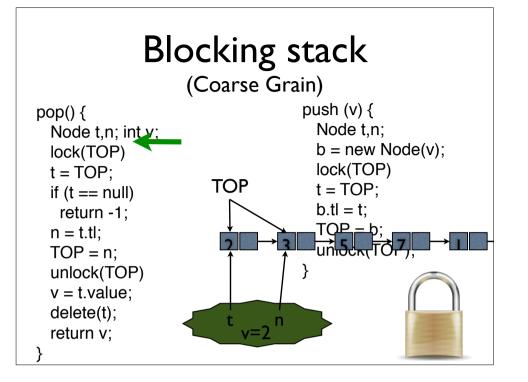
"Testing concurrent software is hard. Even simple tests require invoking methods from multiple threads and worrying about issues such as timeouts and deadlock. Unlike in sequential programs, many failures are rare, probabilistic events and numerous factors can mask potential errors."

JavaOne Technical session

Verification to the rescue?

Types of concurrency

- Disjoint concurrency
- Coarse-grain concurrency
- Fine-grained concurrency
- Non-blocking concurrency



Implementing Locks

Compare and Swap:

CAS(I, t, n) means if (*I == t) { *I = n; return true }

Problems with locks

- Pre-emption
- Bad in high contention
- Priority inversion

Try without locks.

Nonblocking stack

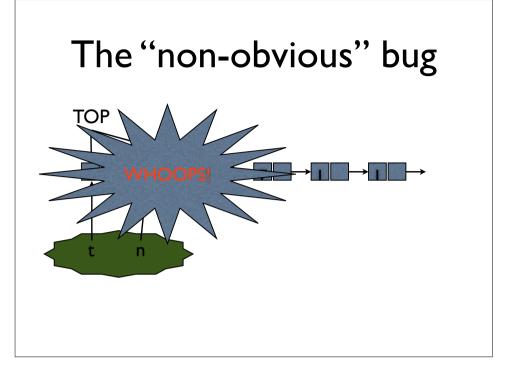
}

pop() {
 Node t,n; int v;
 while(true) {
 t = TOP;
 if (t == null) return -1;
 n = t.tl;
 if (CAS(&TOP,t,n)) {
 v = t.value;
 delete(t); return v;
 }

}

}

push (v) {
 Node t,n;
 b = new Node(v);
 while(true) {
 t = TOP;
 b.tl = t;
 if (CAS(&TOP, t, b))
 break;
 }



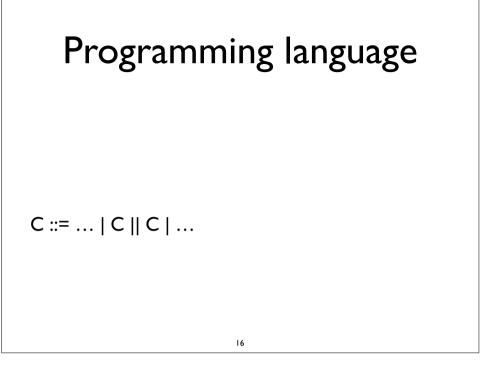
Non-blocking difficult

Several fixes to this algorithm

- Timestamps
- Garbage collector
- DCAS
- Hazard pointers

Disjoint Concurrency

15



Now we extend the language with parallel composition. That is the ability for two threads/processes to be interleaved.

 $\begin{array}{l} C_1 \mid \mid C_2 \; , s, h \rightarrow \; C_1 \; \mid \mid C_2 \; , s', h' \\ \text{if either } C_1, s, h \rightarrow \; C_1 \; , s', h' \; \text{and} \; C_2 = C_2 \; \\ \text{or} \; \; C_2, s, h \rightarrow \; C_2 \; , s', h' \; \text{and} \; C_1 = C_1 \; \end{array}$



 $\left\{ \begin{array}{c} P_1 \end{array} \right\} C_1 \left\{ \begin{array}{c} Q_1 \end{array} \right\} \\ \left\{ \begin{array}{c} P_2 \end{array} \right\} C_2 \left\{ \begin{array}{c} Q_2 \end{array} \right\} \\ \left\{ \begin{array}{c} P_1 \ast P_2 \end{array} \right\} C_1 \mid \mid C_2 \left\{ \begin{array}{c} Q_1 \ast Q_2 \end{array} \right\} \end{array} \\ \mbox{Provided variables used in } C_1 \mbox{ not modified by } C_2 \\ \mbox{ and variables used in } C_2 \mbox{ not modified by } C_1 \end{array}$

The variable side condition prevents races on the stack variables.

The * prevents races on the heap.

Example $\{x \mapsto _*y \mapsto _\}$ $\left\{ \begin{array}{c} x \mapsto \\ [x] := 3 \end{array} \right\} \left\{ \begin{array}{c} y \mapsto \\ [y] := 4 \end{array} \right\}$ $\{ x \mapsto 3 \} \{ y \mapsto 4 \}$ $\{x \mapsto 3 * y \mapsto 4\}$

The variable side condition is trivially satisfied as neither side modifies any variables.

The * is used to ensure that neither thread modifies the same heap.

Parallel Dispose tree

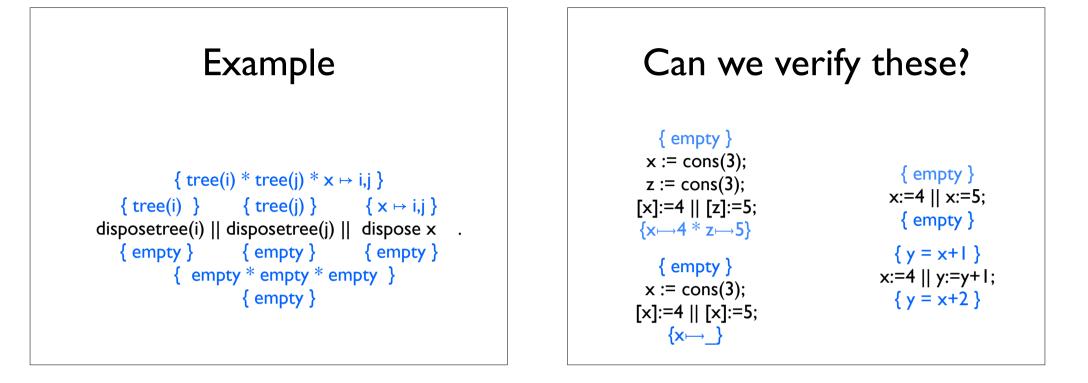
```
{ tree(x) }disposetree(x) { emp } +
  { tree(x) }
  if x != 0 then
    i := [x+1];
    j := [x];
    disposetree(i) || disposetree(j) || dispose x
  { empty }
```

```
19
```

Example

```
{ tree(x) \land x != 0}
{ ∃i,j. tree(i) * tree(j) * x \mapsto i,j }
i := [x+1];
{ ∃j. tree(i) * tree(j) * x \mapsto i,j }
j := [x];
{ tree(i) * tree(j) * x \mapsto i,j }
disposetree(i) || disposetree(j) || dispose x
{ empty }
```

```
Exercise: Prove that the rule
{\exists x. P * E \mapsto x} x := [E] {P * E \mapsto x}
provided E does not mention x.
is sound.
```



Merge sort

```
mergesort(x, n)
if n > 1 then
local m in
m := n/2;
mergesort(x,m) || mergesort(x+m,n-m);
merge(x,m,n-m)
```

Merge sort takes a pointer to an array an a length.

If the array has 1 or 0 elements then it is trivial to sort it. Otherwise, we must recurse. We divide the size of the array into two, and sort the two parts in parallel. Finally, we must merge the arrays.

Merge sort

```
{ array(x,n) }
  mergesort(x, n)
{ sorted_array(x,n) }
```

{ sorted_array(x,m) * sorted_array(x+m,n) }
merge(x,m,n)
{ sorted_array(x,m+n) }

```
We can define array as
array(x,n) ⇔ ⊛<sub>0≤i<n</sub>. x+i ↦ _
```

where

```
⊛<sub>0≤i<0</sub>.P(i) ⇔ empty
```

and

 $\circledast_{0 \leq i < n+1}.P(i) \Leftrightarrow (\circledast_{0 \leq i < n}.P(i)) * P(n)$

That is, $\circledast_{0 \le i < n} . P(i) \Leftrightarrow P(0)^* ... * P(n-1)$

We define a data_array(x,n,f) $\Leftrightarrow \circledast_{0 \le i < n}$. x+i \mapsto f(i)

Here f is used as a function to represent the data contained in the array. We can then define a sorted array as sorted_array(x,n) $\Leftrightarrow \exists f. data_array(x,n,f) \land sorted(f)$

sorted(f) $\Leftrightarrow \forall i. f(i) \le f(i+1)$

Exercise

Given the previous specifications verify the body of mergesort.

The specification does not deal with the resulting array being a permutation, how could you extend the specification?

Concurrent Separation Logic

26

Multiple access

How do we verify a program where several threads want access to the same memory? e.g.

[x] := 43 || [x] := 47

Programming language

C ::= ... | resource r in C | with r when B in C | ...

28

We add two connectives to deal with communication resource r in C

Allocates a lock, r, that can be used inside the command C.

The second

with r when B in C

acquires the lock for the execution of C provided the condition B holds on entry, otherwise it blocks until that condition holds before acquiring the lock. This is also called a critical region.

Resource Rule

 $\frac{\Delta, r: I \vdash \{P\} C \{Q\}}{\Delta \vdash \{P^*I\} \text{ resource } r \text{ in } C \{Q^*I\}}$

We use a context to specify the resource invariant associate to each lock.

 $\Delta ::= r : P | \Delta, \Delta$

We can treat this as a map from resource/lock name r, to its invariant P. This rule can be read as removing some local state and making it shared by the lock r.

Lock Rule

 $\frac{\Delta \vdash \{ (P * I) \land B \} C \{ Q * I \}}{\Delta, r : I \vdash \{ P \} \text{ with } r \text{ when } B \text{ in } C \{ Q \}}$

In this rule, we acquire the lock r, and get the resource's invariant, I, added to our pre-condition. On exit from the lock, we must re-establish the resource's invariant, hence the "* I" in the post-condition. This is similar to the while rule, where we must reestablish the loop invariant after executing the body. Here it is a little different, reestablishing the resource invariant it required, so the next thread to acquire the lock will correctly be able to assume the resource invariant holds.

Question: How do we know the resource invariant will not be modified when the lock isn't acquired?

Caveat: side-conditions

There are subtle variable side-conditions used to allow locks to refer to global variables.

Each variable is either associate to

- a single thread; or
- a single lock.

It can then only be modified and used in assertions by the thread, or while the thread holds the associate lock.

Alternatively, we could encode all variable access into the heap, but this leads to complications in the presentation.

Another alternative is presented in

Variables as resource for Hoare Logic

Parkinson, Bornat, and Calcagno, LICS 2006

where a logic of variables is developed in a similar way to separation logic deals with the heap.

Binary Semaphore

We can encode a semaphore as a critical region

P(s) = with r_s when s=1 do s := 0V(s) = with r_s when s=0 do s := 1

Resource invariant

 $(s=0 \land empty) \lor (s=1 \land Q)$

Initially,

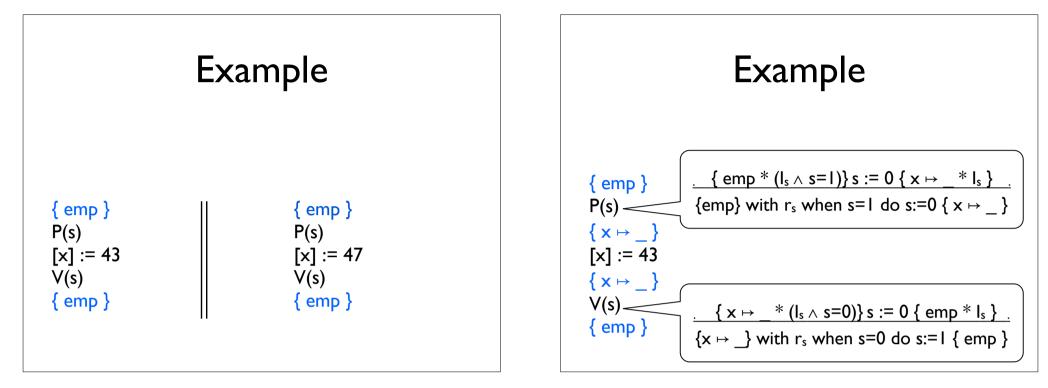
s=0

The variable s is associate with the critical region/lock r_s .

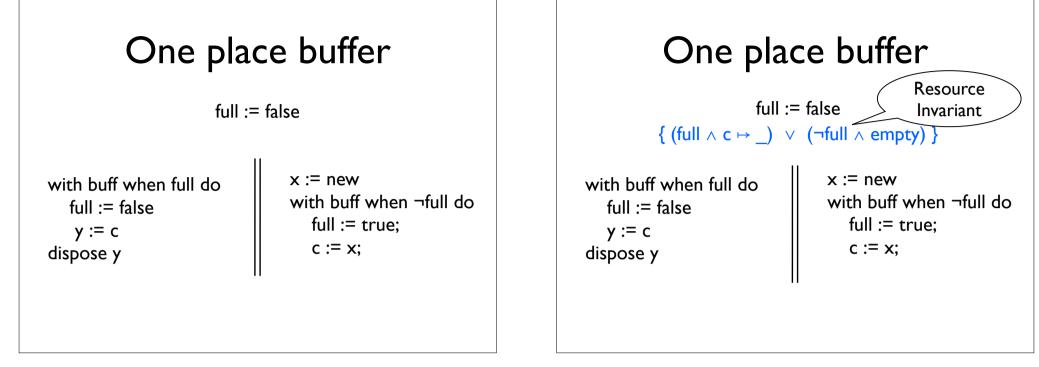
Q is the state protected by the semaphore.

We can specify { emp } P(s) { Q } and { Q } V(s) { emp }

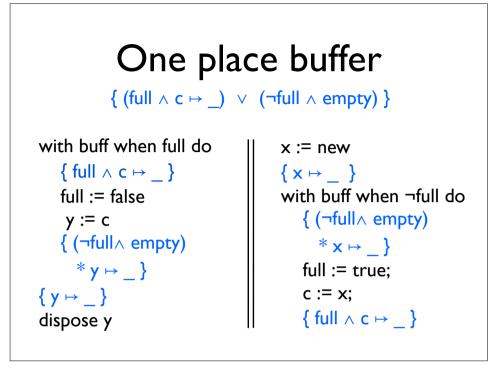
Exercise: Prove the body meets these specifications.



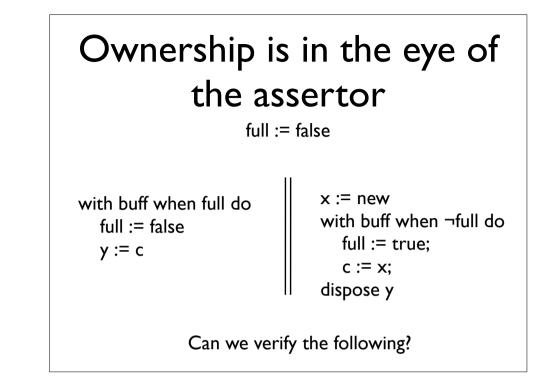
Let Q be $x \mapsto _$ in the resource invariant of the semaphore.



The variable full is associated with the lock, buff.



Upon entry to the critical region, we get the resource invariant added to our current precondition. When we leave the region we must reestablish the resource invariant.



Caveat: precise invariants

The resource invariant associate with a particular lock must be precise.

A formula, P, is precise, iff, for any heap, there is at most one subheap satisfying the formula

 $\forall h_1, h_2, h.$ $h_1 \leq h \land h_2 \leq h \land h_1 \models P \land h_2 \models P \Rightarrow h_1 = h_2$

Rule of conjunction

 $\left\{ \begin{array}{c} P_1 \end{array} \right\} C \left\{ \begin{array}{c} Q_1 \end{array} \right\} \\ \left\{ \begin{array}{c} P_2 \end{array} \right\} C \left\{ \begin{array}{c} Q_2 \end{array} \right\} \\ \left\{ \begin{array}{c} P_1 \land P_2 \end{array} \right\} C \left\{ \begin{array}{c} Q_1 \land Q_2 \end{array} \right\} \end{array}$

We can define an order on heaps as $h_1 \le h \Leftrightarrow \exists h'$. $h_1 * h = h'$

Subtle soundness

Without rule of conjunction logic is sounds with arbitrary resource invariants.

With precise invariants and the rule of conjunction the logic is sound.

Reynolds' counter example

We can prover the following holds with the resource invariant: r: true.

{true} skip {true}

 $\{(\mathsf{emp} \lor \mathsf{x} \mapsto _) * \mathsf{true} \} \mathsf{skip} \{ \mathsf{emp} * \mathsf{true} \}$

{ emp $\lor x \mapsto _$ } with r when true do skip { emp }

Reynolds counter example

From the previous proof we can derive both

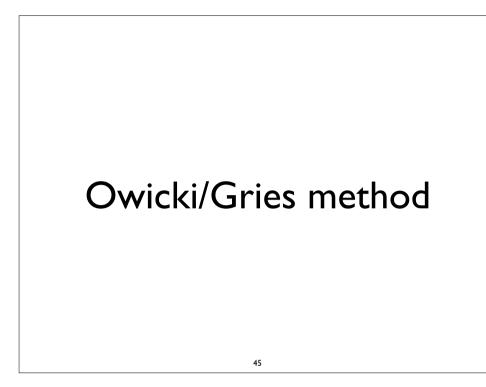
```
{ emp * x \mapsto \_ } with... { x \mapsto \_ }
{ emp * x \mapsto \_ } with... { emp }
```

which with the rule of conjunction leads to a contradiction.

What about racy programs?

Do we want to forbid all races?

Does concurrent separation logic forbid all races?



For this lecture we will ignore the heap.

We will focus on how to remove the draconian restriction on variables from the previous section. As we had the heap these restrictions didn't seem so bad. But without the heap they are very restrictive.

This lecture is based very heavily on Francesco Zappa-Nardelli's presentation.

Example

If we assume assignment is atomic, then is the following true:

{ x = 0 } x := x + 1 || x := x + 2 { x = 3 }

Parallel rule (attempt)

 $\left\{ \begin{array}{c} P_1 \end{array} \right\} C_1 \left\{ \begin{array}{c} Q_1 \end{array} \right\} \\ \left\{ \begin{array}{c} P_2 \end{array} \right\} C_2 \left\{ \begin{array}{c} Q_2 \end{array} \right\} \\ \left\{ \begin{array}{c} P_1 \land P_2 \end{array} \right\} C_1 \parallel C_2 \left\{ \begin{array}{c} Q_1 \land Q_2 \end{array} \right\} \end{array}$

This rule is unsound. Consider

 ${ y=1 } x := 0 { y=1 }$ ${ true } y := 2 { true }$

both hold in Hoare logic, but $\{ y=1 \land true \} x :=0 II y := 2 \{ y=1 \land true \}$ certainly does not hold.

Parallel rule (attempt 2)

 $\left\{ \begin{array}{c} P_1 \end{array} \right\} C_1 \left\{ \begin{array}{c} Q_1 \end{array} \right\} \\ \left\{ \begin{array}{c} P_2 \end{array} \right\} C_2 \left\{ \begin{array}{c} Q_2 \end{array} \right\} \\ \left\{ \begin{array}{c} P_1 \land P_2 \end{array} \right\} C_1 \parallel C_2 \left\{ \begin{array}{c} Q_1 \land Q_2 \end{array} \right\} \end{array}$

Provided $FV(P_1,Q_1)$ not modified by C_1

and $FV(P_2,Q_2)$ not modified by C_2

This rule is unsound. Consider

both hold in Hoare logic, but $\{ y=1 \land true \} (x := y ; y := x) || x := 2 \{ z=1 \land true \}$ certainly does not hold.

The issue is that the intermediate assertion in the proof $\{y=1\}$ x := y; $\{x=1\} \leftarrow$ This is affected by the other thread.

z := x { z=1 }

The assignment interferes with the assertion.

Interference

Do the following commands affect the assertions

	x:=x+l	y:=y+1	x:=x+2	x:=y
x>100				
y=4				
even(x)				
x<30				
x=y				
even(x)∧even(y)				

Interference

C does not interfere with P:

- mod(C) is disjoint from $FV(P) \leftarrow$ too restrictive
- { P } C { P }

The second says the command does not affect the validity of the assertion

Exercise: prove the questions on the previous slide with both definitions.

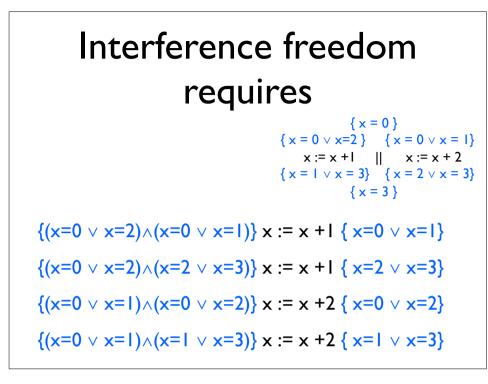
Interference freedom

We define the critical formula of a proof outline Δ proving {P}C{Q}, as Q and every pre-condition of a command.

Given two proof trees $\Delta_1 \Delta_2$, they are interference free if for every critical formula in one, R, and every triple in the other {P}C{Q}, then the triple preserves the formula, {P \land R} C { R }.

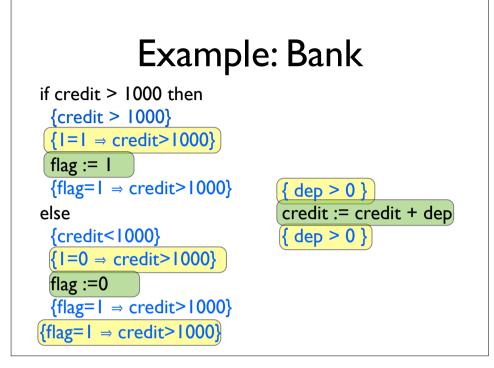
Example

 $\{ x = 0 \} \\ \{ x = 0 \lor x=2 \} \quad \{ x = 0 \lor x = 1 \} \\ x := x + 1 \quad || \quad x := x + 2 \\ \{ x = 1 \lor x = 3 \} \quad \{ x = 2 \lor x = 3 \} \\ \{ x = 3 \}$



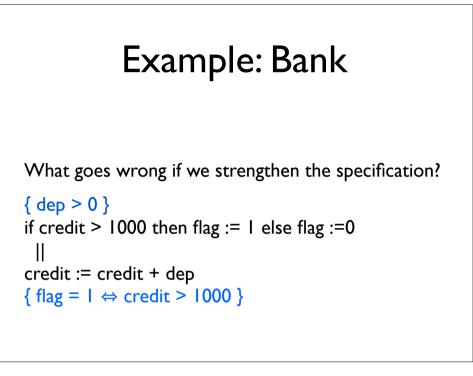
Example: Bank

```
{ dep > 0 }
if credit > 1000 then flag := 1 else flag :=0
||
credit := credit + dep
{ flag = 1 ⇒ credit > 1000 }
```



We have four unique critical assertions, and three commands that update the state.

Exercise: Prove each of the critical assertions is preserved by the commands.



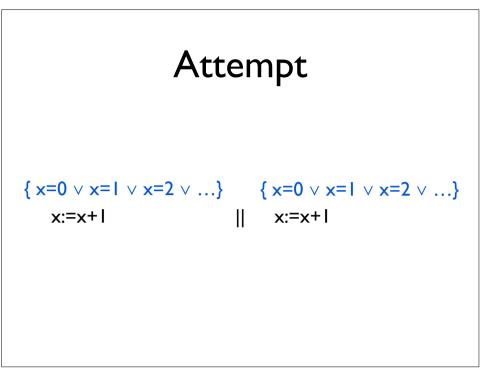
Exercise: Attempt this proof, and illustrate which of the conditions does not hold.

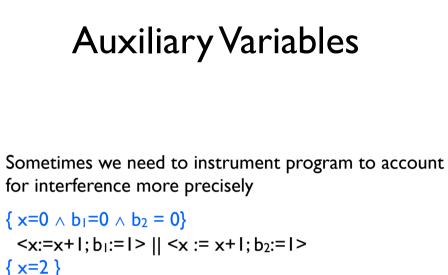


Can you prove the following:

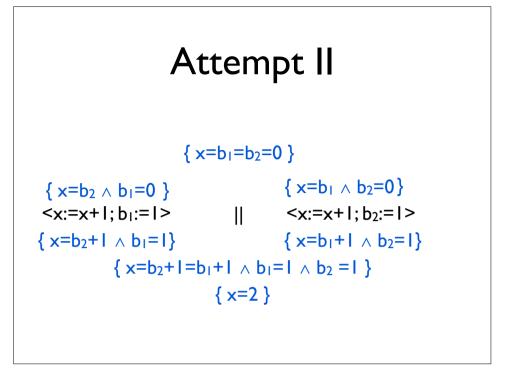
{ x=0 } x:=x+1 || x := x+1 { x=2 }

?





Angle brackets mean the program executes all the operation in one indivisible unit of time. That is, intermediate states are not observable. It is atomic.



Auxiliary Variables

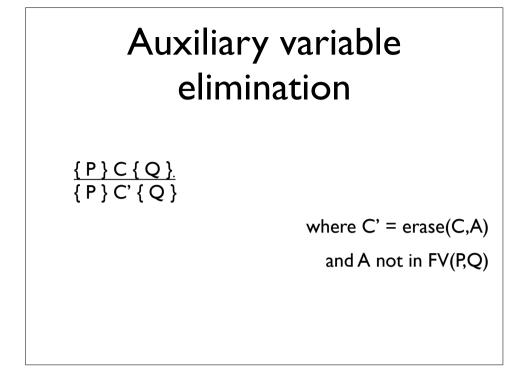
A set of variables, A, is consider auxiliary, if

• the only expressions they appear in, are on the right of an assignment where the target of the assignment is in the set of auxiliary.

We define erase(C,A) as replacing all assignment to an auxiliary by skip.

That is they cannot appear in the guards of loops or if-then-else commands, and their value cannot be assigned to a normal variables.

Alternatively, it can be seen as erase(C,A) no longer mentions A.

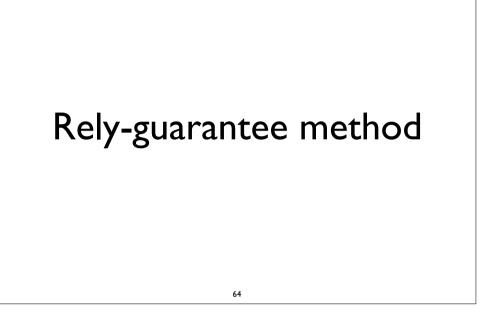


This rule allows us to introduce auxiliary variables in the justification of a program. As we did for the double increment program.

Conclusions

If we have n commands in a thread, and m critical assertions, and t threads how many interference checks would we have to perform?

Is there a more scalable/compositional way?



A good introduction to rely-guarantee can be found in Vafeiadis's award winning dissertation:

Modular fine-grained concurrency verification http://www.cl.cam.ac.uk/techreports/UCAM-CL-TR-726.html

Interference

In Owicki/Gries method each pre-condition needed checking against each command in another thread.

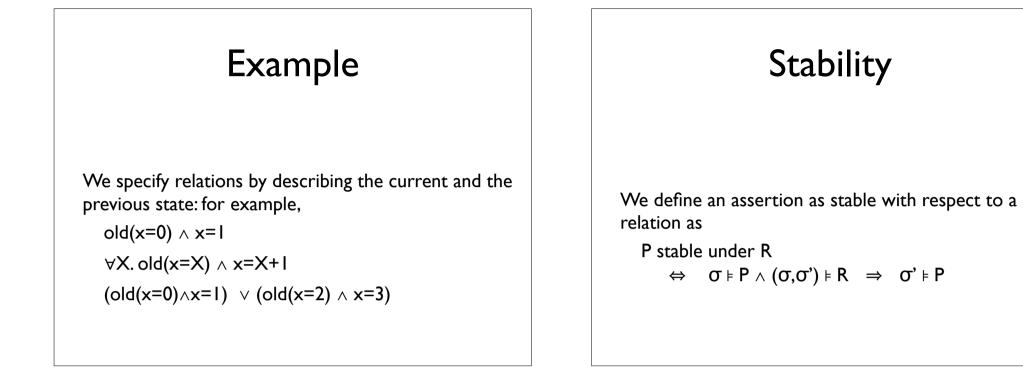
Can we abstract the interference?

Rely-guarantee

Judgements are extended with a concurrent context R, G \vdash { P } C { Q }

- the rely, R, is an abstraction of what the other threads can do; and
- the guarantee, R, is an abstraction of what this thread does.

Both the rely and guarantee are relations.



Stability

Do the following relations preserve the assertions

	x=old(x)+I	x=old(x)+2	id(x) ∧ y=old(y)+I	id(x) ∧ y=old(y)+2
x>100				
y=4				
even(x)				
x<30				
x=y				
$even(x) \land even(y)$				

Parallel Rule

 $\begin{array}{l} G_{1} \subseteq R_{2} \\ G_{2} \subseteq R_{1} \\ R_{1}, G_{1} \vdash \left\{ \ P_{1} \ \right\} C_{1} \left\{ \ Q_{1} \ \right\} \\ \underline{R_{2}, G_{2} \vdash \left\{ \ P_{2} \ \right\} C_{2} \left\{ \ Q_{2} \ \right\} } \\ R_{1} \ \cap \ R_{2}, G_{1} \ \cup \ G_{2} \vdash \left\{ \ P_{1} \ \wedge \ P_{2} \ \right\} C_{1} \ || \ C_{2} \left\{ Q_{1} \ \wedge \ Q_{2} \ \right\} \end{array}$

Parallel Rule

 $\begin{array}{l} G_1 \Rightarrow R_2 \\ G_2 \Rightarrow R_1 \\ R_1, G_1 \vdash \left\{ \begin{array}{c} P_1 \end{array} \right\} C_1 \left\{ \begin{array}{c} Q_1 \end{array} \right\} \\ \frac{R_2, G_2 \vdash \left\{ \begin{array}{c} P_2 \end{array} \right\} C_2 \left\{ \begin{array}{c} Q_2 \end{array} \right\} }{R_1 \land R_2, G_1 \lor G_2 \vdash \left\{ \begin{array}{c} P_1 \land P_2 \end{array} \right\} C_1 \mid \mid C_2 \left\{ Q_1 \land Q_2 \end{array} \right\} } \end{array}$

Assignment

P stable under R Q stable under R $P \land x=old(E) \Rightarrow G$ $\underline{P\RightarrowQ [x:=E]}$ R, G + { P } x := E { Q }

If we consider a logic over relations, we can view it with the logical connectives.

Skip <u>P stable under R</u> R, G ⊦ { P } skip { P }

Surprisingly, we have to modify this rule slightly to maintain soundness of the system.

Example

Let us return to our simple example: x := x + 1 || x := x + 2We can verify this using the following relations $R_1 = (old(x)=0 \land x=2) \lor (old(x)=1 \land x=3) = G_2$ $R_2 = (old(x)=0 \land x=1) \lor (old(x)=2 \land x=3) = G_1$



To show

$$R_1,G_1 + \{x=0 \lor x=2\} x := x + 1 \{x=1 \lor x=3\}$$

We need to prove

- $x=0 \lor x=2$ stable under R_1 ; and
- $x=1 \vee x=3$ stable under R_1 ; and
- $old(x=0 \lor x=2) \land x=old(x+1) \Rightarrow G_1$; and
- $(x=0 \lor x=2) [x:=x+1] \Rightarrow (x=1 \lor x=3)$

How does this compare to Owicki/Gries?

Comparison

Exercise: Prove the second thread meets the specification.

